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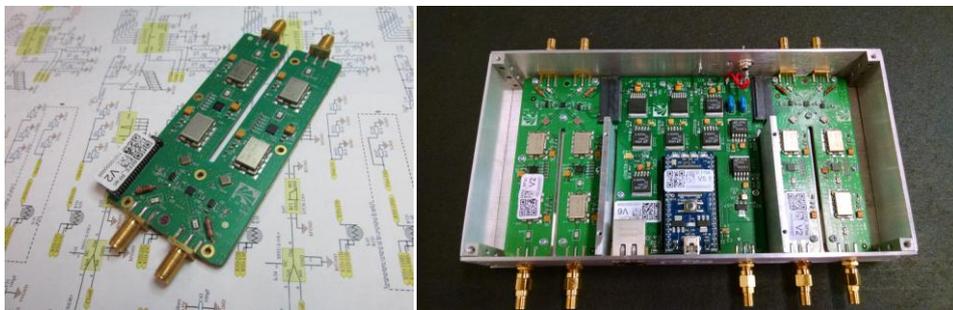
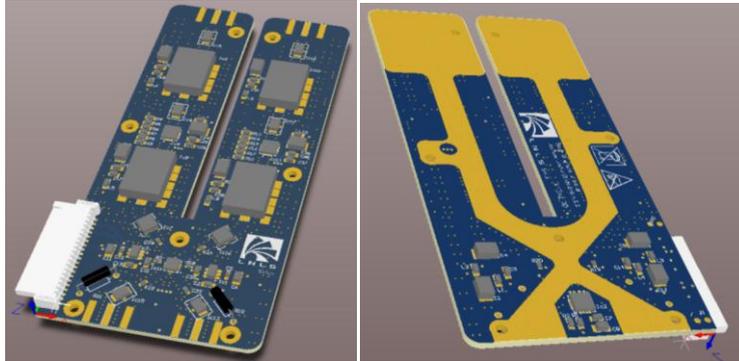
RFFE_v2

RFFE_v2 hardware manual

January 2014 – April 2014

Brazilian Synchrotron Light Laboratory
Beam Diagnostics Group (DIG)

- Design reference name: RFFE_v2
- OHWR link: <http://www.ohwr.org/projects/bpm-rffe>
- Manager: Rafael Antonio Baron
- Last production: Beam Diagnostics Group, Brazilian Synchrotron Light Source, 15 units, jan/2014.



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01/12/2013	0.1	Initial draft.	Rafael A. Baron,
26/10/2014	0.2	Revision of block diagrams	Rafael A. Baron
07/01/2015	0.3	General comments added	Rafael A. Baron

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1. General information

- **About the manual:** This manual is intended to describe about the RFFE_v2 hardware designed for the BPM electronics of the Brazilian Synchrotron Light Source, Sirius Project. There are information about the specific schemes that are implemented on the board, about the devices chosen (when necessary), and about manufacturing process.
- **If some part of the text is important it will be noted with the signals that are described in what follows.**

Conventions



DANGER

Indicates that death or severe personal injury will result if proper precaution are not taken.



Warning

Indicates that death or severe personal injury may result if proper precautions are not taken.



Caution

Indicates that minor personal injury can result if proper precautions are not taken.



Notice

Indicates that damage to equipment can result if proper precautions are not taken.



Information

Indicates information that we think you should have read to save your time by avoiding common problems. Important suggestions that should be followed will also be marked with this sign.

2. Introduction

The RFE electronics is the analog processing part of the BPM electronics system designed by the LNLS Beam Diagnostics Group for the Sirius synchrotron accelerator.

The RFFE electronics is composed by three boards. The RF analog electronics for channels A and C, the analog electronics for channels B and D and by the digital control board. This manual is related to the two RF analog conditioning boards, that are intended to provide gain, calibration and filtering to the RF beam signals that come from 25 meter of cables from the Beam position Monitor.

The two RF analog boards are similar in terms of schematic and layout, except by small adjustments on the interface connector, that is placed on opposed extremes. The RFFE control board is in the middle of the two RF analog boards.¹

Follows the RFFE specifications.

Table 1: Specifications of the BPM RF Front-End electronics².

Parameter	Value
Dynamic Range	40 dB
Noise Figure ³	< 10 dB
Crosstalk	< -40 dB
Bandwidth (3 dB)	80 MHz
1 dB Compression Point	> 20 dBm
MTBF in user beam delivery	20 years

2.1 Hardware Characteristics:

- Two RF channels providing Active Gain Control with attenuation ranging from 0 dB up to 30 dB.
- The central frequency can be changed by a footprint compatible SAW filter. From 400 MHz up to 550 MHz.
- High linear design, achieving less than ± 0.001 dB nonlinearity over -35 dBm to -10 dBm
- On-chip Crossbar switching that improves drift and noise performance from \sim DC up to half the switching frequency
- Input LPF before RF active devices are used in order to avoid peak voltages
- Physically separated channels to provide better electromagnetic isolation
- High Reliability connectors. Footprint compatible with other standard connectors
- Temperature control for the input LPF in order to keep its insertion loss constant

¹More details about the mechanical enclosure can be seen on section 3.7.

²All the specifications are for the standard configuration of attenuators (10 dB). Temperature operation: -20 °C to 50 °C.

³The Noise Figure depends on the attenuator configuration.

2.2 Safety Instructions



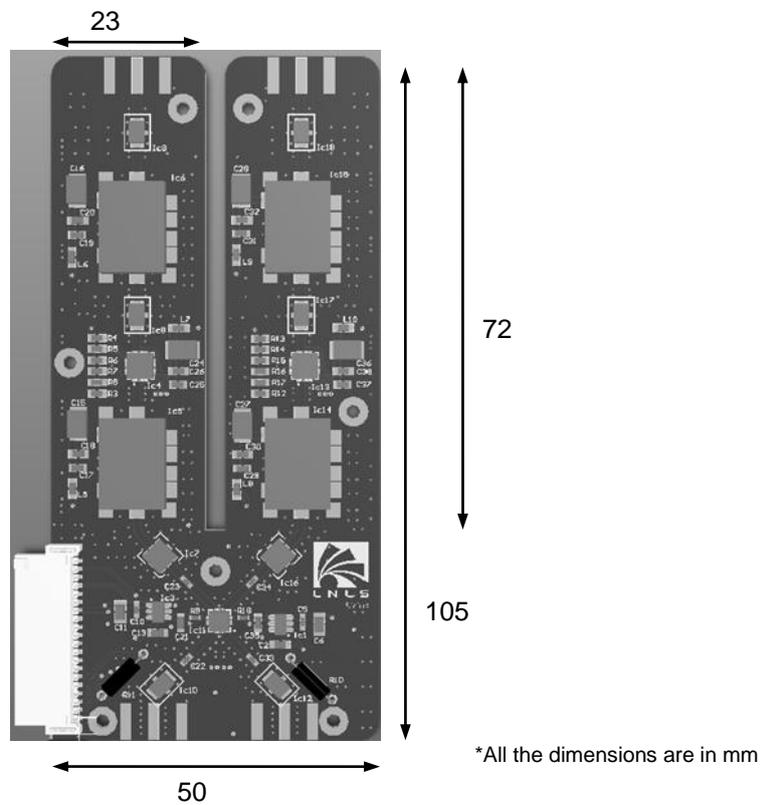
DANGER

Do not operate this electronics in potentially explosive atmosphere

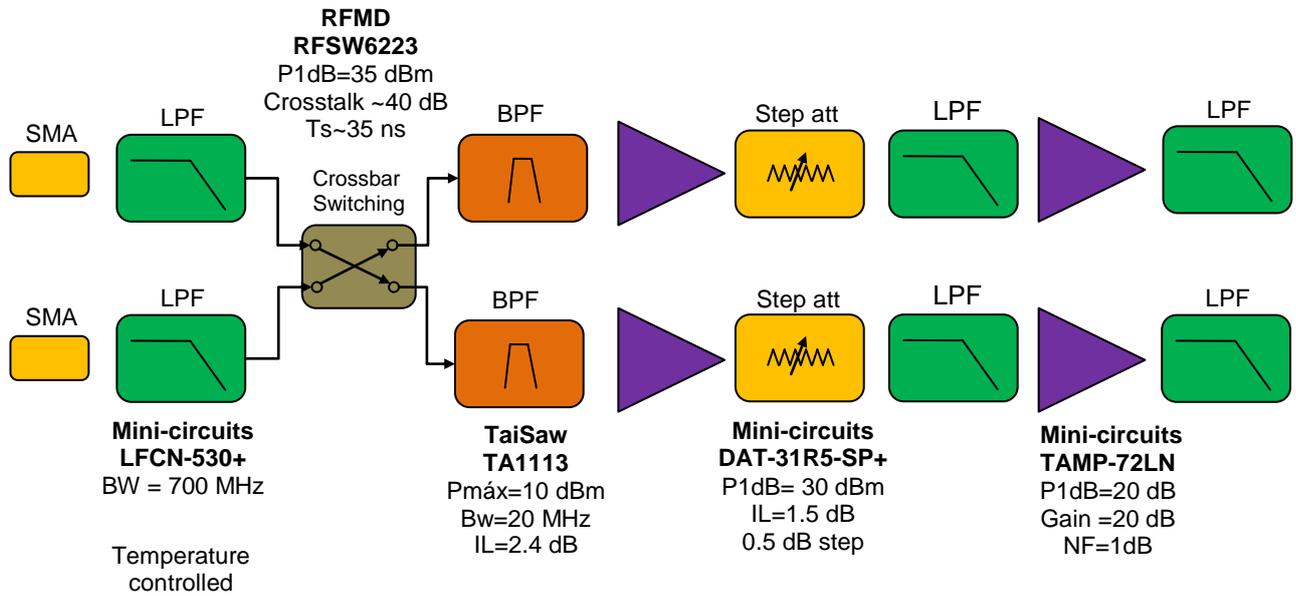
3. Technical Overview

On this section it will be described about the hardware characteristics and detailed schematic description

3.1 Mechanical Drawings



3.2 Block Diagram



- Input Low pass filter
 - The peak voltages on the input of the electronics can excite a nonlinear behavior. For these reason a LPF is necessary before the first amplifying stage.
- Switches
 - High linear (P1dB>30 dBm), well-matched (S11<-20 dB), high isolated (crosstalk < -40 dB), fast (ts < 100 ns) and stabilized switches were necessary to achieve a good performance.
- Amplifiers
 - High linear, low noise amplifier is required for the first amplifying stage of the electronics. For the last amplifying stage, it is better to use higher P1dB amplifiers in order to better use the full scale of the ADC.

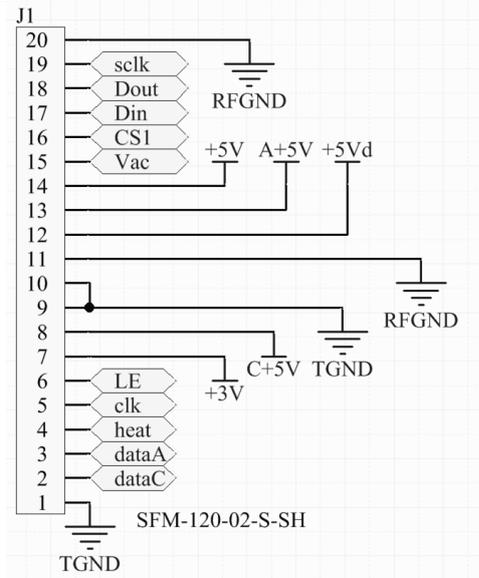


Notice

- Do not exceed the Max input Power of 10 dBm on the electronics. It can permanently damage the devices.

3.3 Interfaces

The board has an interface connector that provides the clean power supply for RF amplifiers, attenuators and switches (3V and 5 V), digital signals for attenuators programming, SPI interface for the temperature monitor IC, two different grounding nodes (one for RF and another for digital signals) and a signal for the feedback loop of the temperature controller.

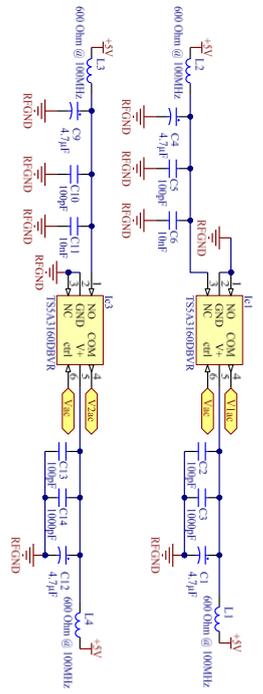


Pin number	Pin Name	Function	Current/voltage ratings
1	TGND	Ground node for digital and temperature control circuits.	
2	dataC	Data pin. Attenuator, channel C ⁴ .	
3	Data	Data pin. Attenuator, channel C.	
4	Heat	Temperature control Pin. The temperature control loop is implemented via resistor as actuator. The Heat pin.	
5	Clk	Clock pin for the serial interface of the RF attenuators.	
6	LE	Latch enable pin for the RF attenuators.	
7	+3V	Voltage pin for the RF attenuators. It go to the supply pin via an input filtering stage to avoid Crosstalk.	1 mA máx
8	C+5V	Input pin to the RF amplifiers, channel C. This pin go to supply pin vi an input filtering stage to avoid Crosstalk.	250 mA máx
9	TGND		
10	TGND		
11	RFGND	Ground node for the RF devices.	
12	+5Vd	5 Volts input supply for the digital devices. Temperature monitor.	10 mA máx
13	A+5V	Input pin to the RF amplifiers, channel A. This pin go to supply pin vi an input filtering stage to avoid Crosstalk.	250 mA máx
14	+5V	Supply voltage for the control pin of the crossbar switch.	1 mA máx
15	Vac	Control Pin for the crossbar switch. It controls the analog switch that provide for the crossbar switch a clean control voltage.	10 mA máx
16	CS1	Chip select for the SPI communication with the temperature monitor ⁵ .	
17	Din	Data input for the SPI communication with the temperature monitor IC.	
18	Dout	Data output for the SPI communication with the temperature monitor IC.	
19	Sclk	Clk pin for the SPI communication with the temperature monitor IC.	
20	RFGND		

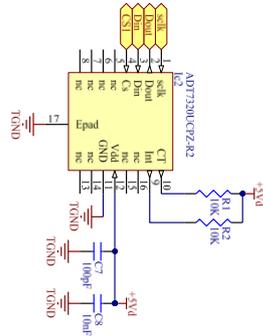
⁴ Refer to the RF attenuator datasheet for details. Minicircuits, part number: DAT-31R5-SP+.

⁵ Refer to the temperature monitor IC datasheet for details about the SPI interface. Analod Devices, part number: ADT7320.

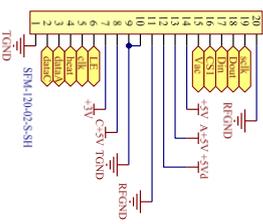
3.4 Schematics



Buffer for switches

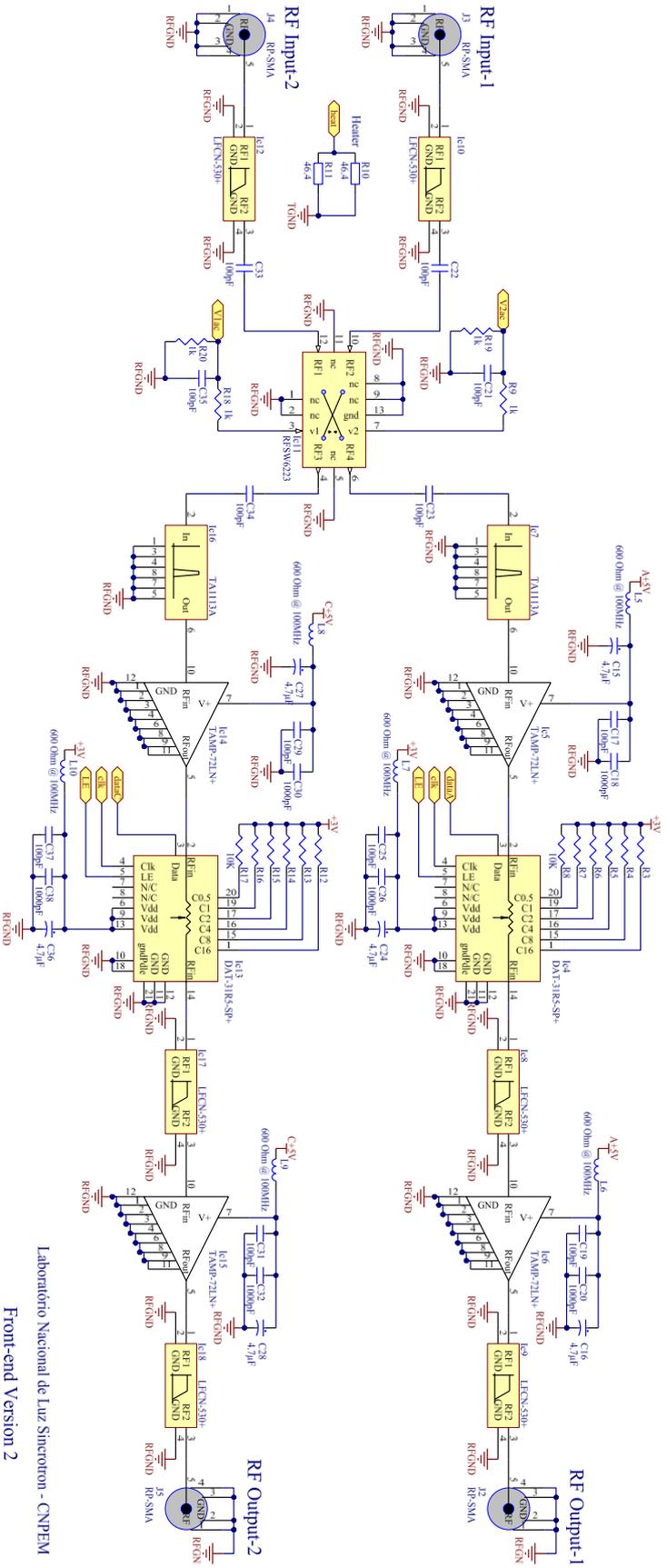


Temperature Sensor



Connector

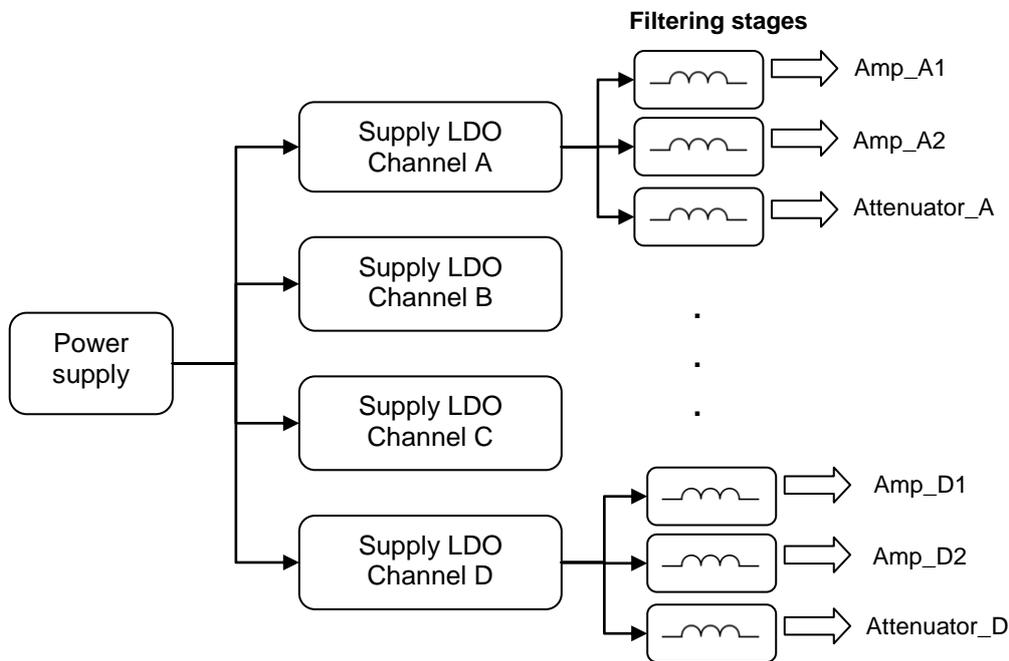
RF Channels



Laboratório Nacional de Luz Síncrotron - CNPEM
 Front-end Version 2
 I/1
 RAB

3.4.1 Power supply

General block diagram of the Power Supply



Power Supply Schematic:

- One input filtering stage for each channel/device, isolating each active device

3.4.2 Switching scheme

- The crossbar switching is implemented using DPDT switches from RFMD, RFSW6223.
- The “Buffer for switches” was designed because the switch is supplied and controlled through the same pin. This scheme provides a fast transition between 0 (0 V) and 1(5 V) state with a clean supply.
- Low *On* resistance switch is used to swap between clean supply and control voltage and the ground.
- Different capacitors in parallel were used because as the RF switch has a very small power consumption, the small capacitors feed it during the transition time. After the transient, the RF switch is fed by a clean supply.

3.4.3 Temperature sensor

- The temperature sensor is reliable and has high repeatability.
- *The only long term data the manufacturer have is for 500 hours (in the data sheet). Drift was specified at 0.0073 °C.*
- *Long term drift typically drifts as a \sqrt{time} (in hours). The drift for 20 years is estimated as 0.14 °C⁶.*

3.4.4 Connector

- The connectors are SAMTEC high reliability ones
- 1.27 mm pitch. Compatible with standard footprints.

• ⁶ *This is based on typical value taken during characterization, and is certainly not production tested or guaranteed.*

3.4.5 Mean Time between failures - MTBF

MTBF estimation based on MILD-HDBK-217[1]

Devices	Qty/RFFE	MTBF (million hours @25 °C)	MTBF (million hours @30 °C)	MTBF (million hours @35 °C)	MTBF (million hours @50 °C)	MTBF (million hours @60 °C)
ADC-10-4+	0	2083.3	1974.8	1873.6	1557.8	1348.1
BPF-C495	0	213.3	205.1	196.4	171.1	154.23
DAT-31R5-SP+	4	144	92	59	15.64	6.42
GSWA-4-30DR	0	157.2	142.8	125.8	79.1	47.7
HSWA2-30DR	0	758	481	312	81.15	33.3
LFCN-530+	12	170.2	170.2	170.2	170.2	170.2
SBTC-2-10L	0	156.5	151.3	146.4	131.2	121.1
TAMP-72LN	8	144.3	139.4	134.5	129.6	119.8
LT1764A	4	1097	1097	1097	1097	1097
Capacitors / resistors	50	1000	800	700	600	500
TCA6424	2	4180	3800	3600	3300	3000
DAC7554	2	1000	800		600	500
LT3080/LTC1964	10	1000	800		600	500
MBED	1	200	190		170	160
Capacitors / resistors (control board)	50	1000	800		600	500
System Reliability (Million hours)		0.941513426	0.786924247	0.687492433	0.479162684	0.308904357
System MTBF estimation (years)		107.478	89.8315	78.480	54.6989	35.26



Notice

- Do not operate the electronics at temperatures higher than 50 °C. It will decrease the expected lifetime.

3.5 Typical Performance Characteristics

The results presented on this section show the typical characteristics for an RF channel of the RFFEv2 electronics.

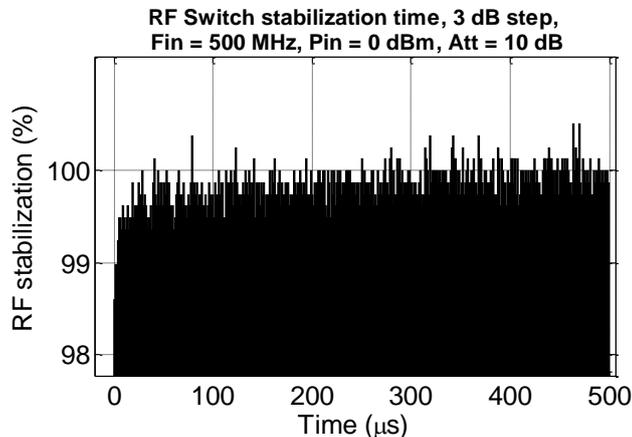
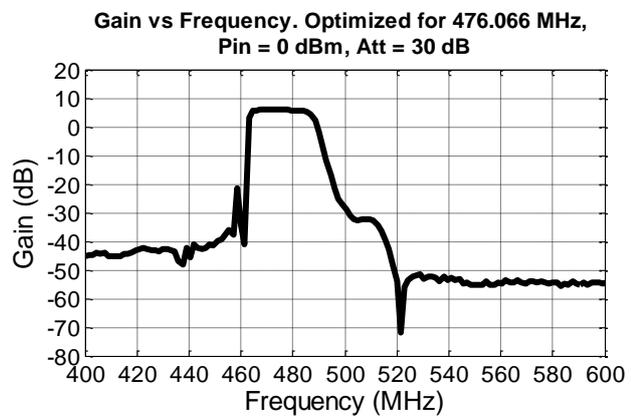
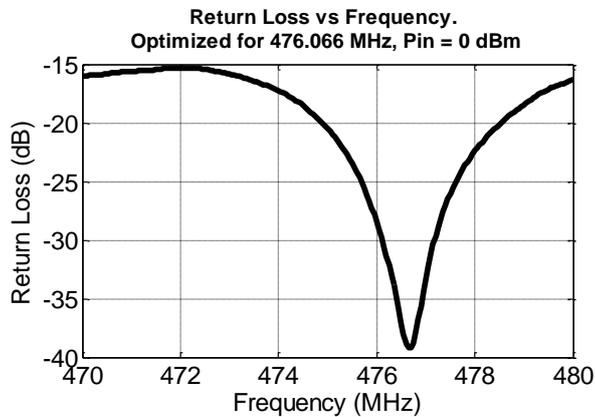
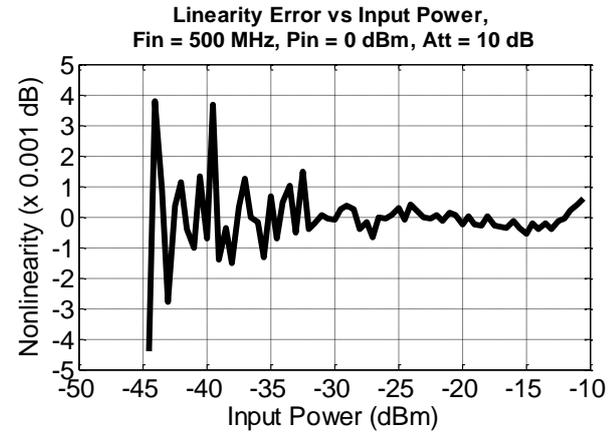
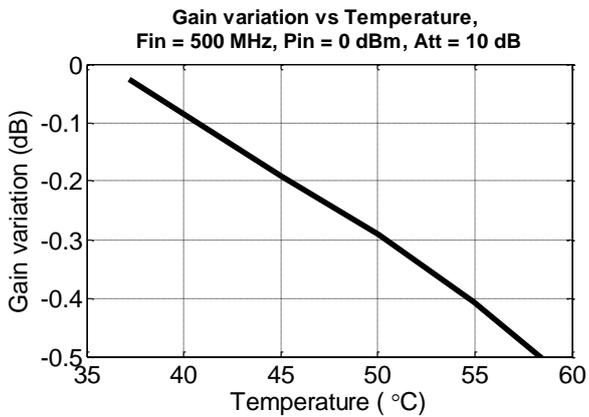
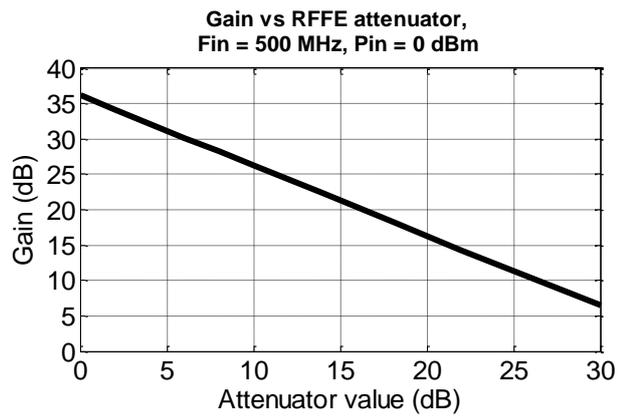
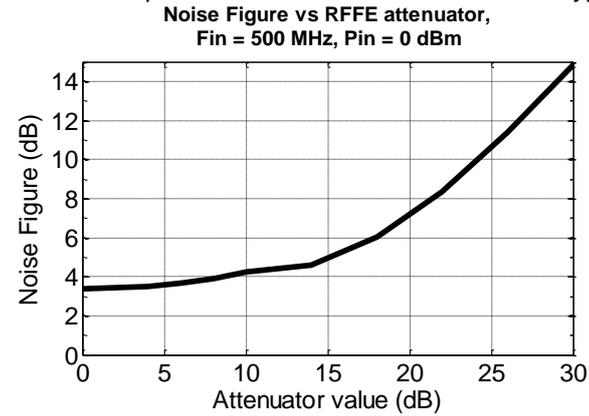


Figure: Stabilization time of the RF switch, ~400 µs for 100% of RF. 90 % of RF stabilization time is ~40 ns.

3.6 PCB Design

- Symmetric switching scheme
- Designed with Rogers RO4350 20 mils thickness laminate on RF layer
- Improved grounding schemes
- Temperature control on the LPF before the switching scheme
- Temperature sensor on the bottom side
- Enclosure as shielding and thermal stabilizer
- SMA connectors screwed on the Enclosure
- 4-layers, 117x50 mm.

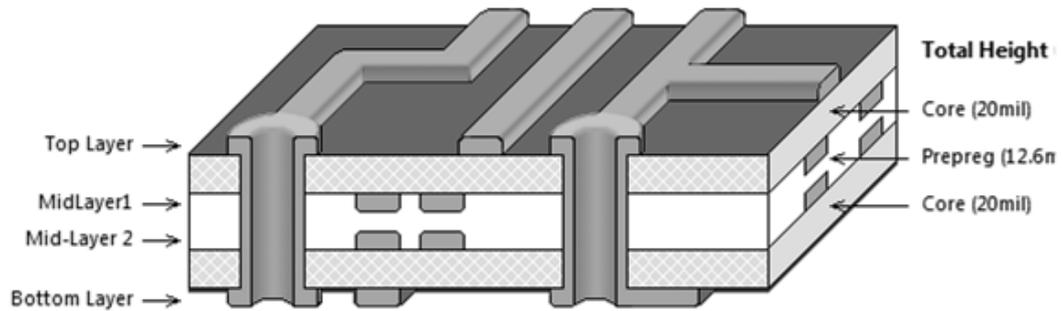


Figure: Layer stack manager

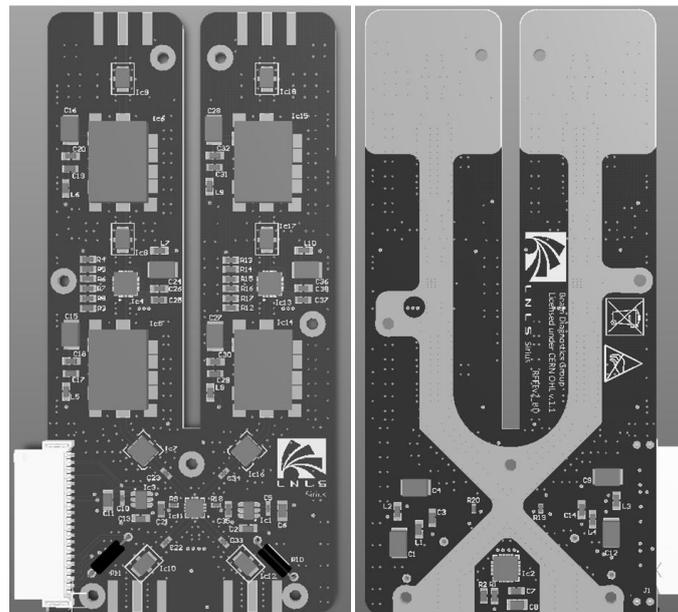
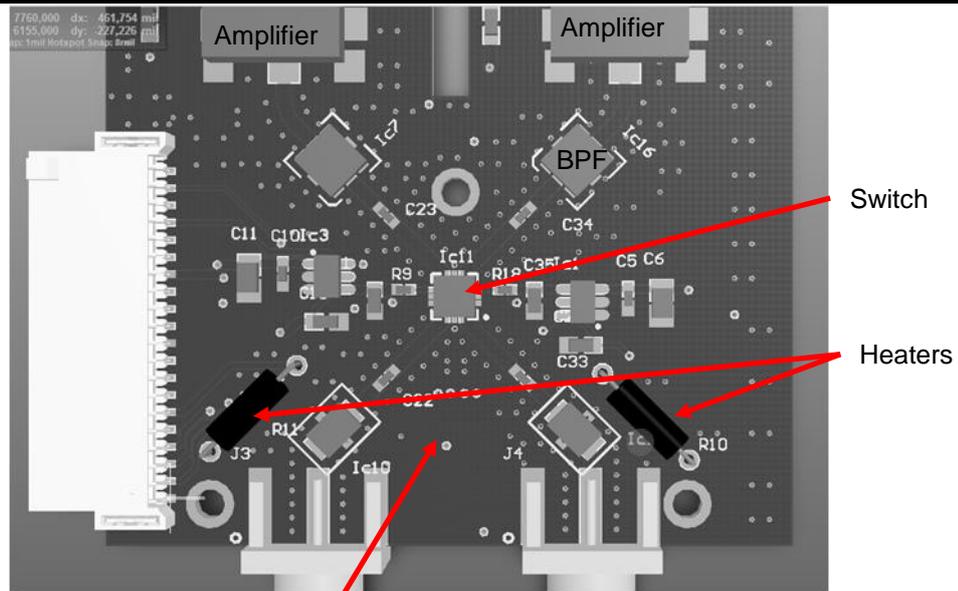
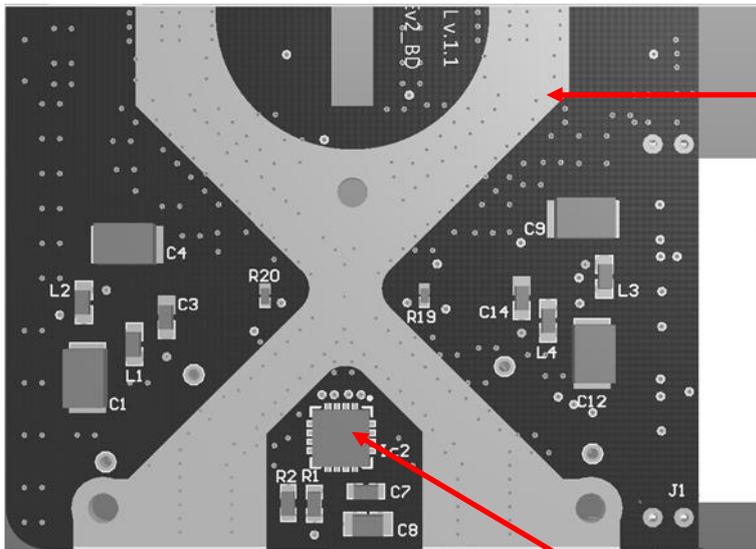


Figure: Top and bottom side



Temperature sensor (bottom side)

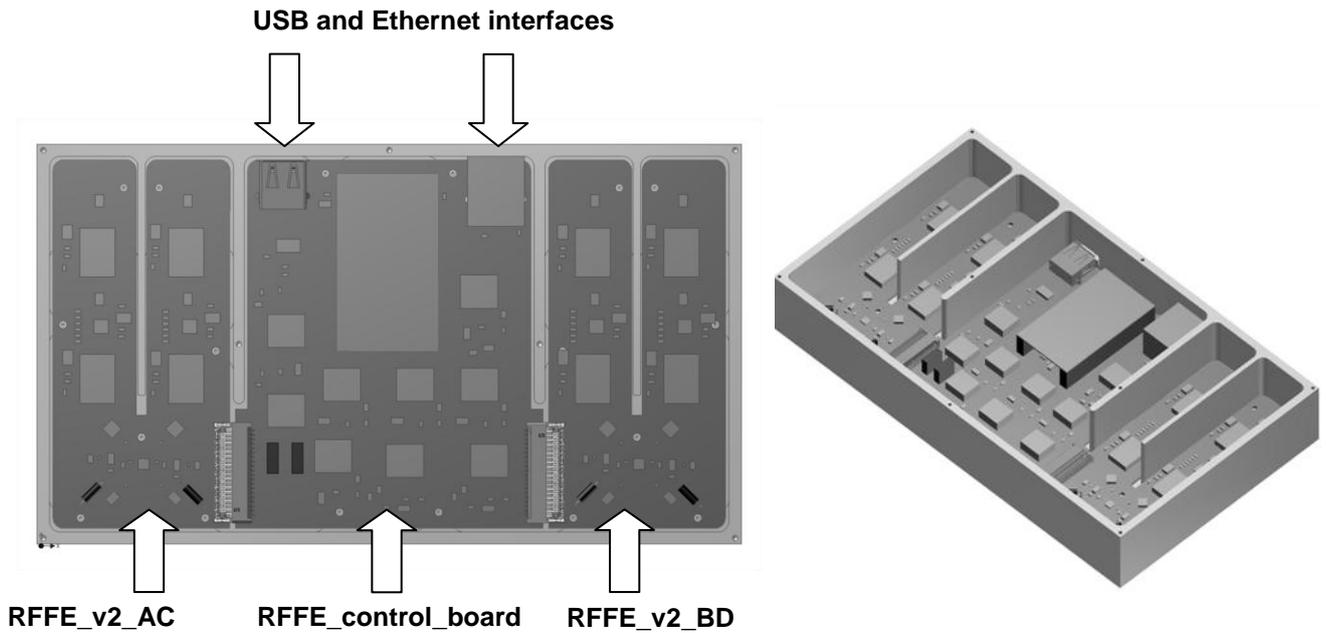


Exposed ground for mechanical and electrical contact with the aluminum enclosure. Grounding and Thermal improvements

Temperature sensor

3.7 Mechanical Assembly

The boards are assembled in a customized mechanical enclosure that provide appropriate shielding and thermal dissipation for the hardware.



4. PCB Fabrication Requirements

Design references

<i>Name</i>	RFFE_V2		
<i>File name(s)</i>	RFFE_v2_AC	RFFE_v2_BD	
<i>Designer</i>	Rafael Antonio Baron		
<i>E-mail</i>	dig@lnls.br		
<i>Fone</i>	+55 19 3512-5071	Date	30/01/2014

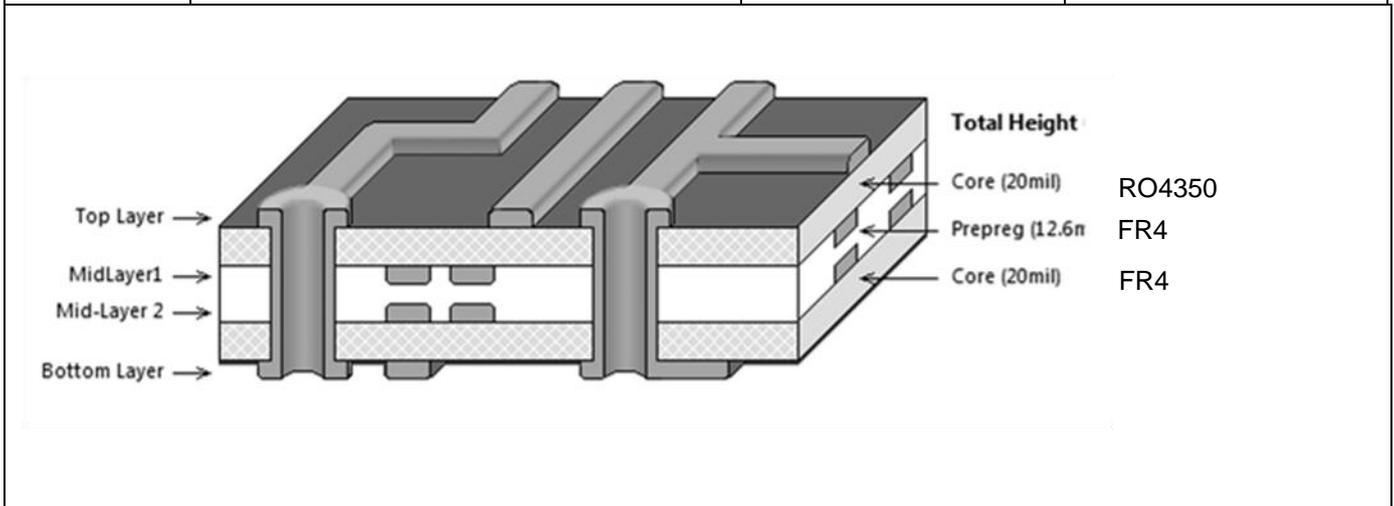
Mechanical characteristics

External size (mm)	50 mm x 105 mm
Thickness (mm)	1.6 mm
Multilayers	4 layers
Min track width (mm/mils)	
Min Hole size (mm/mils)	
Laminate	RO4350 on top layer
Pre-preg	FR-4
Finish Copper	
External layers (μm)	35 μm
Holes walls (μm)	25 μm
Internal Layers-Planes (μm)	35 μm
Internal Layers-Signals (μm)	35 μm

Board finishing requirements	
Silkscreen on top layer (color)	Green
Silkscreen on bottom layer (color)	Green
Surface Finishing	ENIG – Electroless Nickel / Immersion Gold according to IPC-4552
Thickness	Ni: 3 µm min, 6 µm máx. Au: 0.05 µm min, 0.125 µm máx

Additional Information	
Impedance test	No
Packaging requirements	No
Documentation to be delivered	No
Additional control quality requirements	No

Board Stackup Information			
		Laminate/pre-preg	Thickness (mm/mils)
Layer 1	RF signals		
Layer 2	RF Ground Plane	RO4350	20 mils
Layer 3	Digital signaling	FR4	20 mils
Layer 4	Ground Plane + Digital signals	FR4	20 mils



5. References

[1] "Military Handbook - Reliability Prediction of Electronic Equipment," Department of Defense - United States of America, 1990.